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Brain tissue temperature dynamics during functional activity and possibilities for optical measurement techniques

Greggory H. Rothmeier
Georgia State University

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Regional tissue temperature dynamics in the brain are determined by the balance of the metabolic heat production rate and heat exchange with blood flowing through capillaries embedded in the brain tissue, the surrounding tissues and the environment. Local changes in blood flow and metabolism during functional activity can upset this balance and induce transient temperature changes. Invasive experimental studies in animal models have established that the brain temperature changes during functional activity are observable and a definitive relationship exists between temperature and brain activity. We present a theoretical framework that links tissue temperature dynamics with hemodynamic activity allowing us to non-invasively estimate brain temperature changes from experimentally measured blood-oxygen level dependent (BOLD) signals. With this unified approach, we are able to pinpoint the mechanisms for hemodynamic activity-related temperature increases and decreases. In addition to these results, the potential uses and limitations of optical measurements are discussed.

INDEX WORDS: Functional magnetic resonance imaging, Blood oxygen level dependent, Brain temperature, Functional near-infrared spectroscopy
Brain tissue temperature dynamics during functional activity and possibilities for optical measurement techniques

by

Greggory H. Rothmeier

A Thesis Submitted in Partial Fulfillment of the Requirements for the Degree of Master of Science in the College of Arts and Sciences Georgia State University 2012
Brain tissue temperature dynamics during functional activity and possibilities for optical measurement techniques

by

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Committee: Brian Thoms
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Office of Graduate Studies
College of Arts and Sciences
Georgia State University
May 2012
Dedication

This is dedicated to my parents who made me go to college and to Brooke who inspired me to go to graduate school. If I wasn’t lucky enough to have all of you I would probably be working for Geek Squad.
Acknowledgments

I want to thank my advisors A. G. Unil Perera and Mukesh Dhamala for their guidance and leadership through my graduate school career. Likewise, I must thank everyone in Dr. Perera’s and Dr. Dhamala’s labs for always being helpful over the past couple of years. Thank you. The work presented here was done while under the support of the GSU Brains and Behavior fellowship and a faculty seed grant awarded to Mukesh Dhamala and A. G. Unil Perera.
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<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BOLD</td>
<td>Blood Oxygen Level Dependent</td>
</tr>
<tr>
<td>CBF</td>
<td>Cerebral Blood Flow</td>
</tr>
<tr>
<td>CMRO$_2$</td>
<td>Cerebral metabolic rate of O$_2$</td>
</tr>
<tr>
<td>CSF</td>
<td>Cerebral Spinal Fluid</td>
</tr>
<tr>
<td>deoxyHb</td>
<td>Deoxyhemoglobin</td>
</tr>
<tr>
<td>fMRI</td>
<td>Functional Magnetic Resonance Imaging</td>
</tr>
<tr>
<td>fNIRS</td>
<td>Functional Near-Infrared Spectroscopy</td>
</tr>
<tr>
<td>OLM</td>
<td>Oxygen Limitation Model</td>
</tr>
<tr>
<td>oxyHb</td>
<td>Oxyhemoglobin</td>
</tr>
<tr>
<td>ROI</td>
<td>Region of Interest</td>
</tr>
<tr>
<td>TRS</td>
<td>Time Resolved Spectroscopy</td>
</tr>
</tbody>
</table>
1 Introduction

Since its invention in the 1950’s [4] and later development in the 1970’s [5], Magnetic Resonance Imaging (MRI) has allowed physicians and scientists a detailed view within the human body. Beginning in the 1990’s, it was realized that changes in the local metabolic state affect the local magnetic resonance and provide an indication of brain activity [6, 7]. This is possible because hemoglobin is diamagnetic in an oxygenated state and paramagnetic when deoxygenated. Thus as the local concentration of deoxyhemoglobin changes, the local magnetic susceptibility is also altered.

By combining this effect with a discovery made earlier in 1986 [8], MRI becomes a powerful tool for measuring brain activity. Fox and Raichle [8] found that with an increase in neuronal activity came an increase in local cerebral blood flow (CBF) that exceeded the increase in cerebral metabolic rate of oxygen (CMRO\textsubscript{2}). The change in local tissue oxygenation created by uncoupled changes in CBF and CMRO\textsubscript{2} is referred to as the blood oxygen dependent (BOLD) response [7]. A schematic of the model for generation of the fMRI BOLD response is provided in Fig. 1.1.

A stimulus within a region of the brain induces either an excitatory or inhibitory (or a combination) neuronal response. An increase in excitatory neuronal activity triggers an increase in CBF which overcompensates for the increase in CMRO\textsubscript{2} [8]. Conversely, an increase in inhibitory neuronal activity does not induce a change in CBF. Increasing CMRO\textsubscript{2} increases the concentration of deoxyhemoglobin (deoxyHb) while increasing CBF delivers more blood to the tissue thereby increasing the concentration of oxyhemoglobin (oxyHb) and increasing local tissue oxygenation. The change in blood oxygenation is detected by the fMRI as the BOLD response [7].

Along with changes in the BOLD response, changes in CBF and CMRO\textsubscript{2} also affect the local tissue temperature. As glucose is metabolized, heat is released that is primarily
Figure 1.1: Generation of the fMRI BOLD response from changes in neuronal activity. Black arrows indicate a causal relationship while colored dashed-arrows indicate existing models for the relationship. The orange line (●) shows the model proposed by Sotero and Iturria-Medina [1] to calculate cerebral blood flow and metabolism and the blue line (●) shows how the model proposed by Collins et al. [2] is used to calculate temperature. Modified after Sotero and Trujillo-Barreto [3].

The human brain relies on CBF to remove excess heat from the brain [9]; thus, a change in rate of blood flow will affect how quickly heat can be dissipated (or delivered as we’ll explore in section 2.3). Since both BOLD and temperature are dependent on CBF and CMRO₂, it is possible to use the BOLD data collected to calculate the temperature change. As will be further discussed in section 2.3.1, the resulting temperature change cannot be easily characterized for the entire brain because it’s behavior is spatially dependent.

Experimental measurements of activity-induced brain temperature changes are mixed in whether an increase in brain activity increases or decreases local tissue temperature [10, 11, 12, 13, 14]. Current temperature models predict that an increase in activity will result in a decrease in temperature [1, 15, 16]. This is generally the prediction because these models
generalize the resting-state conditions of the region of interest (ignoring spatial dependence) which puts the blood temperature below the resting state tissue temperature. An increase in blood flow then acts as a coolant for the tissue and lowers the temperature (more on this in section 2.1).

An accurate model for brain temperature could be valuable for many clinical applications [17]. A seizure has been shown to induce a large change in brain temperature [18], so if an fMRI measurement is made of a patient during a seizure, the temperature change could be calculated. It has been shown that treating severe head injuries with induced mild hypothermia greatly improves the clinical outcome [19]. A similar result has been shown in patients being treated for brain ischemia [20, 21] and stroke [22]. Additionally, it has been shown that mild hypothermia can be neuroprotective in infants undergoing heart surgery [23]. During treatment, the brain temperature is currently inferred by indirect means. This can be achieved by measuring the temperature of the temporalis muscle [24], the tympanic canal [25, 26], nasopharynx [27] or by the use of a venous bulb in the jugular [28, 29]. While commonly used, their reliability has not been validated [26, 29]. A model of brain temperature could let physicians better understand the relationship between brain temperature and the measurements they are able to make. This could make hypothermia-based treatments more effective since the brain temperature could be better controlled.

I will explore a model which calculates temperature using the fMRI BOLD response for the entire brain, thereby accounting for spatial dependencies. Additionally, in chapter 3 I’ll explore optical measurement techniques including functional near-infrared spectroscopy (fNIRS) and the use of thermal imaging cameras to measure activity-induced brain temperature changes.
2 Calculating Temperature Changes using the fMRI BOLD Response

2.1 Introduction

Using fMRI to find brain temperature is enticing because it is noninvasive. Existing efforts to model temperature changes can be categorized into two classes. The first class approaches the problem by considering a single region of interest (ROI) deep within the brain (single-voxel approach) while the second approach considers the brain and head as an entire system (multi-voxel approach). A voxel is a volumetric pixel that is used to subdivide the head. The single-voxel approach is unable to explain the experimental observation of an increase in temperature during a task; however a multi-voxel approach is able to account for this observation.

2.1.1 Single-Voxel Methods

Numerous single-voxel approaches have been created [1, 15, 16] which differ largely only in their formulation of Penne’s Bioheat Equation [30]. Although different approaches consider different contributions to the temperature change, they all narrow the problem down to a single region of interest. By simplifying the model, the heat equation can be simplified and the calculation is much easier to undertake. However, since the brain is not homogenous, the values used for parameters such as heat production and thermal conductivity are taken from an average of the tissues. As a result, this reduces the level of accuracy these models can achieve.

The most recently published iteration of a single-voxel model was published by Sotero and Iturria-Medina [1] in 2011. Their formulation of Penne’s Bioheat Equation is as follows [30, 1].

\[
C_{tissue} \frac{dT(t)}{dt} = (\Delta H^o - \Delta H_b)CMRO_2 \left|_0 m(t) - \rho b C_b CBF \right|_0 f(t)(T(t) - T_a) - \frac{C_1}{\tau} (T(t) - T_b) \tag{2.1}
\]
where $C_{tissue}$ is the specific heat of the tissue, $\Delta H^\circ$ is the enthalpy released in the oxidation of glucose, $\Delta H_b$ is the enthalpy used to release oxygen from hemoglobin, $CMRO_2 \big|_0$ is the metabolic rate of oxygen at rest, $\rho_b$ is the blood density, $C_b$ is the specific heat of blood, $CBF|_0$ is the cerebral blood flow at rest, $T_a$ is the arterial blood temperature, $C_T$ is the specific heat for the tissue, and $\tau$ is a time constant for conductive heat loss. The values used are provided in Table 2.2.

One advantage of using Eq. (2.1) is that the resting state temperature can be analytically determined by substituting $\frac{dT(t)}{dt} = 0$ [1].

$$T_0 = T_a + \frac{(\Delta H^\circ - \Delta H_b)CMRO_2 |_0}{\rho_B C_B CBF |_0}$$

(2.2)

If the values provided in Table 2.2 are substituted into Eq. (2.2), a resting temperature of 37.3057°C is found (using $T_a = 37.0000$°C). Regardless of the arterial blood temperature, since the second term of Eq. (2.2) is always positive the resting state temperature will always be greater than the arterial blood temperature. Thus, an increase in blood flow will remove heat from the ROI, thereby lowering the temperature. As will be further discussed in section 2.3.1, this is an acceptable result for the majority of the brain; however a multi-voxel approach reveals that a region of the brain exists where a single-voxel model is unable to predict temperature changes. Since it is a simpler model than a multi-voxel model, it is easier to first understand the principles of Penne’s Bioheat Equation using this model before discussing how it can be applied to the entire head.

While Eq. (2.1) appears complicated, conceptually Penne’s Bioheat Equation can be easily understood:

$$heat \ capacity \ * \ change \ in \ temperature = heat \ generated \ by \ metabolism$$

$$- \ heat \ lost \ due \ to \ convection \ - \ heat \ lost \ due \ to \ conduction$$

$$- \ heat \ lost \ due \ to \ radiation$$

(2.3)
The system is a balance between heat generation (metabolism) and heat transfer (conduction, convection and radiation). The direction of heat transfer by convection is determined by the difference between the voxel temperature and the arterial blood temperature \((T(t) - T_a)\). Similarly, the direction of heat transfer by conduction is determined by the difference between the voxel temperature and the temperature of the surrounding tissue \((T(t) - T_0)\). Since \(T_a\) is less than \(T_0\), an increase in blood flow \((f(t))\) will remove heat from the voxel thereby decreasing the temperature. Conversely, an increase in metabolism \((m(t))\) without a corresponding change in blood flow, will result in tissue warming. Equation (2.1) omits the effect of radiation because the contribution is small compared to the other terms. As we will see in section 3.2, mid-infrared photons are reabsorbed by tissue within \(\sim 10–100\ \mu m\) (Fig. 3.5) so any energy lost due to radiation does not travel very far compared to the ROI size.

### 2.1.2 Multi-Voxel Methods

The multi-voxel approach to calculating brain tissue temperature alleviates many of the issues that a single-voxel approach has. The most prominent advantage a multi-voxel approach has is a result of it accounting for a voxel’s location relative to the surface of the head and other voxels. By accounting for a voxel’s location, the same BOLD response in two different locations can have vastly different effects on the local tissue temperature (more on this in section 2.3.1).

Multi-voxel methods use a three-dimensional implementation of Penne’s Bioheat Equation \([2]\).

\[
\rho c \frac{dT}{dt} = k \nabla^2 T - \rho_{\text{blood}} f(t) w_{\text{blood}} (T - T_{\text{blood}}) + m(t) Q_m
\]

where \(\rho\) is the tissue density, \(c\) is the specific heat of the voxel, \(k\) is the thermal conductivity, \(\rho_{\text{blood}}\) is the blood density, \(w\) is perfusion by blood, \(c_{\text{blood}}\) is the specific heat of blood, \(T_{\text{blood}}\) is the arterial blood temperature, and \(Q_m\) is the baseline metabolic heat production. \(f(t)\) and \(m(t)\) are the time-dependent changes in blood flow and metabolism. These two factors determine the short-term change in temperature and are calculated from the fMRI BOLD.
response; however what makes this approach more complete than a single-voxel approach is that the relatively slow conductive heat loss makes for a different equilibrium temperature at each voxel. This effect can only be captured by considering the entire head. The approach we use is a multi-voxel approach, so more details about this model are discussed in section 2.2.

2.2 Our Approach

Our approach [31, 32] combines a multi-voxel model (section 2.1.2) with a model for calculating the change in metabolism and blood flow from the BOLD response. Penne’s Bioheat Equation (Eq. (2.4)) [30, 1] includes three terms. The first and second terms describe heat exchange by conduction to surrounding tissues (or air) and convection to blood, respectively. The third term describes heat generated by metabolism. On shorter time scales, the first two terms dominate and are sufficient for determining activity-induced temperature changes; however, the third term becomes important on longer time scales because it plays a role in determining the resting-state temperature.

Conductive heat transfer to surrounding tissues is a comparatively slow process, but on larger time scales, conduction plays an important role in determining the resting state temperature. When calculating the temperature change, it is important to first have an accurate resting state temperature since it can either be greater than or less than the arterial blood temperature. By considering the entire head, the model we use is able to accurately determine a resting state temperature for each voxel, enabling far more accurate temperature calculations than what is capable with single-voxel approaches.

Figure 2.1 gives a schematic of the temperature calculation procedure. The orange blocks represent the required data. The first thing to be done is establish the resting-state temperature for each voxel within the head. The details of this procedure are given in section 2.2.2, but in summary a T1 contrast image is segmented using SPM8 (Fig. 2.2) and is combined with tissue-specific parameters (Table 2.1). The resulting dataset is then used to determine the resting-state temperature by repeatedly applying Eq. (2.4) until the temperature stabilizes for all voxels.
The resting-state time slices from the fMRI BOLD dataset are averaged to create a resting state representative slice. The remaining BOLD data is then normalized to this in order to have the normalized change in BOLD response \( \frac{\Delta S}{S_0} \) in Eq. (2.16)). This can then be used with Eqs. (2.9), (2.15) and (2.16) to create a time series for the change in blood flow and metabolism. More details about this procedure are given in section 2.2.3.

The following sections provide a detailed explanation of the theory behind our modeling approach. The code used to implement this procedure is provided and documented in appendix A.
2.2.1 Preparing the model of the head

In order to begin the temperature calculating procedure, a model of the head must first be created. Using SPM8 (http://www.fil.ion.ucl.ac.uk/spm/), we segmented a T1 contrast image of the head into five different tissue types: bone, cerebral spinal fluid, gray matter, white matter and soft tissue. It was assumed that soft tissue voxels that are in contact with air are more appropriately labeled as skin, so in total we are left with a model of the head.

<table>
<thead>
<tr>
<th>Tissue</th>
<th>$f_0$ 100 ml/(g min)</th>
<th>$\rho$ kg/m³</th>
<th>$c$ J kg⁻¹ °C⁻¹</th>
<th>$k$ W m⁻¹ °C⁻¹</th>
<th>$Q_m$ W/m³</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bone</td>
<td>3</td>
<td>1,080</td>
<td>2,110</td>
<td>0.65</td>
<td>26.1</td>
</tr>
<tr>
<td>Cerebrospinal Fluid</td>
<td>0</td>
<td>1,007</td>
<td>3,800</td>
<td>0.50</td>
<td>0</td>
</tr>
<tr>
<td>Gray Matter</td>
<td>67.1</td>
<td>1,035.5</td>
<td>3,680</td>
<td>0.565</td>
<td>15,575</td>
</tr>
<tr>
<td>White Matter</td>
<td>23.7</td>
<td>1,027.4</td>
<td>3,600</td>
<td>0.503</td>
<td>5,192</td>
</tr>
<tr>
<td>Muscle</td>
<td>3.8</td>
<td>1,041</td>
<td>3,720</td>
<td>0.4975</td>
<td>687</td>
</tr>
<tr>
<td>Skin</td>
<td>12</td>
<td>1,100</td>
<td>3,150</td>
<td>0.342</td>
<td>1,100</td>
</tr>
</tbody>
</table>

Table 2.1  Tissue-specific parameters used to calculate the temperature change (values from Collins et al. [2]).
separated into six tissue types (Fig. 2.2). The advantage this has is that we are able to use tissue specific parameters when doing the calculations, thereby improving the accuracy of the results. The parameters used are available in Table 2.1. The code used to create the head matrix is discussed in appendix A.1.

2.2.2 Calculating the equilibrium temperature

The first step in calculating the temperature change is to know the resting state temperature for each voxel within the head. Our approach was to have the initial temperature for all tissue voxels set to 37°C and air voxels are kept at 24°C. The starting temperature of the tissue does not affect the final resting state temperature; however, starting off at drastically different values could greatly increase the calculating time required before the temperature stabilizes. The finite difference implementation of Penne's Bioheat Equation (Eq. (2.4)) is used to update the temperature (derivation provided in section 2.2.4). The temperature is updated until the temperature for every voxel has stabilized ($\frac{dT}{dt} < 10^{-6}$ °C/s). Since temperature changes due to changes in neuronal activity are typically greater than $10^{-2}$ °C, a change in temperature less than $10^{-6}$ °C/s is sufficiently small that transient temperature changes are negligible and temperature can be considered stabilized. The code used to calculate the equilibrium temperature is detailed in appendix A.3.

2.2.3 Calculating Metabolism and Blood Flow Changes from the BOLD response

This is the critical step where we use fMRI BOLD data to calculate the normalized change in metabolism and blood flow. The method used [1] is an assemblage of a couple other works [33, 34, 35, 36, 37, 38]. It starts by using the relation between metabolism and blood flow proposed by Buxton et al. [33]:

$$m(t) = f(t) \frac{E(t)}{E_0}$$

(2.5)
<table>
<thead>
<tr>
<th>Parameter</th>
<th>Meaning</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$T_a$</td>
<td>Arterial blood temperature</td>
<td>37°C</td>
</tr>
<tr>
<td>$C_{tissue}$</td>
<td>Tissue Heat Capacity</td>
<td>3.664 J/(gK)</td>
</tr>
<tr>
<td>$\Delta H^\circ$</td>
<td>Enthalpy released by oxidation of glucose</td>
<td>$4.710^5$ J</td>
</tr>
<tr>
<td>$\Delta H_b$</td>
<td>Enthalpy used to release O$_2$ from hemoglobin</td>
<td>$2.810^4$ J</td>
</tr>
<tr>
<td>CMRO$_2$</td>
<td>Cerebral metabolic rate of O$_2$ consumption at rest</td>
<td>$0.026310^{-6}$ mol/(gs)</td>
</tr>
<tr>
<td>$\rho_b$</td>
<td>Blood density</td>
<td>1.05 g/cm$^3$</td>
</tr>
<tr>
<td>$C_B$</td>
<td>Blood heat capacity</td>
<td>3.894 J/(gK)</td>
</tr>
<tr>
<td>$\tau$</td>
<td>Time constant for conductive heat loss from the ROI to the surrounding tissue</td>
<td>190.52 s</td>
</tr>
<tr>
<td>a, b, c</td>
<td>Parameters of the gamma function fitted from $E(f)$ vs. $f$</td>
<td>0.4492, 0.2216, −0.9872</td>
</tr>
<tr>
<td>A</td>
<td>Maximum BOLD signal change</td>
<td>0.22</td>
</tr>
<tr>
<td>$\alpha$</td>
<td>Steady state flow-volume relation</td>
<td>0.4</td>
</tr>
<tr>
<td>$\beta$</td>
<td>Field-strength dependent parameter</td>
<td>1.5</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Variable</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>m(t)</td>
<td>CMRO$_2$ normalized to baseline</td>
</tr>
<tr>
<td>f(t)</td>
<td>CBF normalized to baseline</td>
</tr>
<tr>
<td>T(t)</td>
<td>Temperature</td>
</tr>
<tr>
<td>W(t)</td>
<td>Lambert W Function</td>
</tr>
<tr>
<td>$\Delta S(t) / S_0$</td>
<td>Change in BOLD signal normalized to rest</td>
</tr>
</tbody>
</table>
where \( E_0 \) is the oxygen extraction at rest and \( E(f) \) is

\[
E(f) = 1 - (1 - E_0)^{\frac{1}{f(t)}}
\]  

(2.6)

in accordance with the oxygen limitation model \([34]\). Combining Eq. (2.5) with Eq. (2.6) yields

\[
m(t) = \frac{f(t)}{E_0} \left[ 1 - (1 - E_0)^{\frac{1}{f(t)}} \right]
\]  

(2.7)

Sotero and Iturria-Medina \([1]\) goes about solving Eq. (2.7) by adjusting \( E(t) \) data generated by Eq. (2.6) and fitting it to the gamma function for the \( f \) range \((0.7–2.0)\) that is within experimentally reported values \([35, 36, 37]\):

\[
\frac{E(f)}{E_0} = a f^c(t) e^{-bf(t)}
\]  

(2.8)

where \( a, b \) and \( c \) are fitting parameters (values provided in Table 2.2). From this approximation we have the final form of metabolism:

\[
m(t) = a f^{c+1}(t) e^{-bf(t)}.
\]  

(2.9)

As proposed by Davis et al. \([38]\), the BOLD signal changes \((\Delta \frac{S(t)}{S_0})\) can be described in terms of \( m(t) \) and \( f(t) \):

\[
\frac{\Delta S(t)}{S_0} = \frac{S(t) - S_0}{S_0} = A(1 - f^{\alpha-\beta}(t)m^\beta(t))
\]  

(2.10)

Substituting Eq. (2.9) into Eq. (2.10) yields

\[
f(t)e^{-\frac{b\beta}{\alpha+\beta}f(t)} = \left( \frac{A - \frac{\Delta S(t)}{S_0}}{Aa^\beta} \right)^{\frac{1}{\alpha+\beta}}
\]  

(2.11)
where \( A \) is the maximum change in BOLD signal. Multiplying each side by \(-\frac{b\beta}{\alpha + \beta c}\) gives

\[
-\frac{b\beta}{\alpha + \beta c} f(t) e^{-\frac{b\beta}{\alpha + \beta c} f(t)} = -\frac{b\beta}{\alpha + \beta c} \left( \frac{A - \Delta S(t)}{S_0} \right)^{\frac{1}{\alpha + \beta c}}
\]

(2.12)

which can be solved by using the Lambert W function

\[
z = W(x)
\]

(2.13)

where \( W(x) \) is a solution for \( z \) in the equation

\[
ze^z = x
\]

(2.14)

Finally, \( f(t) \) is obtained from Eq. (2.12)

\[
f(t) = \frac{\alpha + \beta c}{b\beta} W(y(t))
\]

(2.15)

where

\[
y(t) = -\frac{b\beta}{\alpha + \beta c} \left[ \frac{(A - S(t)}{S_0} - 1 \right]^{\frac{1}{\alpha + \beta c}}
\]

(2.16)

is a function of the BOLD signal. Using Eqs. (2.9), (2.15) and (2.16) allows for the metabolism and blood flow to be calculated from the BOLD signal (values used are provided in Table 2.2).

In order to process the files, the BOLD dataset is stored as a separate NIFTI (*.nii) file for each time step. The first step in processing the data for temperature calculations is to determine a resting state BOLD signal \((S_0)\). The resting state is calculated by taking the voxel-wise mean of the data when the subject is at rest (i.e. the first and last 20 seconds). This results in one data set where each voxel is a mean of all of the voxels at the location over time \((S_0)\). In order to calculate the metabolism and blood flow, the BOLD dataset...
needs to be normalized to this resting state ($\frac{\Delta S(t)}{S_0}$).

Once $\frac{\Delta S(t)}{S_0}$ is known for each time step, Eqs. (2.9), (2.15) and (2.16) can be used to calculate the metabolism and blood flow. The implementation of this procedure is discussed in appendix A.2.

### 2.2.4 Calculating the change in temperature in the active brain

As discussed in section 2.1.2, the foundation of the model is Penne’s Bioheat Equation, Eq. (2.4). The metabolism and blood flow time-courses calculated in section 2.2.3 are used to scale the baseline heat production and blood profusion. This, in turn, induces a change in the temperature.

Penne’s Bioheat Equation (Eq. (2.4)) is implemented using the first-order forward finite difference method:

$$
\dot{T}(t) \approx \frac{T(t + l) - T(t)}{l}
$$

where $T(t)$ is the temperature at time $t$ and $l$ is the time step size. Next, we can approximate $\nabla^2 T$ by using the second order central finite difference method applied for each coordinate:

$$
\frac{\partial^2 T(t; x, y, z)}{\partial x^2} \approx \frac{T(t; x + h, y, z) - 2T(t; x, y, z) + T(t; x - h, y, z)}{h^2}
$$

$$
\frac{\partial^2 T(t; x, y, z)}{\partial y^2} \approx \frac{T(t; x, y + h, z) - 2T(t; x, y, z) + T(t; x, y - h, z)}{h^2}
$$

$$
\frac{\partial^2 T(t; x, y, z)}{\partial z^2} \approx \frac{T(t; x, y, z + h) - 2T(t; x, y, z) + T(t; x, y, z - h)}{h^2}
$$

where

$$
\nabla^2 T = \frac{\partial^2 T(t; x, y, z)}{\partial x^2} + \frac{\partial^2 T(t; x, y, z)}{\partial y^2} + \frac{\partial^2 T(t; x, y, z)}{\partial z^2}
$$

and the step size in each coordinate direction is given by $h$. In the case of processing BOLD data, $h$ is the voxel size. Equation (2.19) can be substituted into Penne’s Bioheat Equation (Eq. (2.4))

$$
\rho c \dot{\rho} = k_x \frac{\partial^2 T}{\partial x^2} + k_y \frac{\partial^2 T}{\partial y^2} + k_z \frac{\partial^2 T}{\partial z^2} - \rho_{\text{blood}} f(t) w_{\text{blood}} (T - T_{\text{blood}}) + m(t) Q_m
$$
where $\dot{T}$ is the first-derivative of temperature with respect to time, $k_x$ is the thermal conductivity in the x-direction, $k_y$ is the thermal conductivity in the y-direction and $k_z$ is the thermal conductivity in the z-direction. Substituting Eqs. (2.17) and (2.18) into Eq. (2.20) yields

$$\frac{\rho c}{l} \frac{T(t + l; x, y, z) - T(t; x, y, z)}{l} \approx \frac{1}{h^2} [k_x(T(t; x + h, y, z) - 2T(t; x, y, z) + T(t; x - h, y, z)) + k_y(T(t; x, y + h, z) - 2T(t; x, y, z) + T(t; x, y - h, z)) + k_z(T(t; x, y, z + h) - 2T(t; x, y, z) + T(t; x, y, z - h))]$$

$$- \rho_{blood} f(t) w_{blood}(T - T_{blood}) + m(t)Q_m \quad (2.21)$$

which is then rearranged to solve for $T(t + l; x, y, z)$

$$T(t + l; x, y, z) \approx T(t; x, y, z) + \frac{l}{\rho ch^2} [k_x(T(t; x + h, y, z) - 2T(t; x, y, z) + T(t; x - h, y, z))$$

$$+ k_y(T(t; x, y + h, z) - 2T(t; x, y, z) + T(t; x, y - h, z))$$

$$+ k_z(T(t; x, y, z + h) - 2T(t; x, y, z) + T(t; x, y, z - h))]$$

$$- \rho_{blood} f(t) w_{blood}(T - T_{blood}) + m(t)Q_m \quad (2.22)$$

The time step size ($l$) can be picked arbitrarily, however the spatial step size ($h$) is limited to the voxel spacing.

The final equation (Eq. (2.22)) gives a method for calculating the next time step ($T(t + l)$) from the current time step ($T(t)$) for each voxel. By using the central difference to solve $\nabla^2 T$, the voxels on all six sides of the current voxel are considered in the heat conduction. The implementation of this equation is discussed in appendix A.4.1.

2.3 Results

In order to understand the behavior of the model, we first applied it simulated BOLD data that was generated by convolving a boxcar function with the hemodynamic response function
provided by SPM8. After we understood the behavior of the model, we then applied it to experimental BOLD data that was collected by Dhamala et al. [39].

2.3.1 Using Synthetic BOLD Data

To better understand the behavior of the tissue temperature model and the characteristics of temperature changes, BOLD activity was simulated in two ways: (i) from a nonlinear hemodynamic model [40] using stimulus or response function, or (ii) by convolving a boxcar function with the canonical hemodynamic response function provided by SPM 8 and corresponding temperature changes were calculated. Figure 2.3(c,d) shows a typical simulated BOLD response used (green curve) along with the change in temperature (blue) for two voxels at different locations in the brain (locations indicated by Fig. 2.3(a)).

Although both voxels have the same BOLD data, the demonstrate contrasting changes in temperature. This can be best understood by considering the equilibrium temperature of each voxel. Figure 2.3(b) is a plot of the equilibrium temperature (blue line) along a line passing through the head (path indicated by the teal line in part (a) of the same figure). The vertical red lines indicate the boundary between the brain and surrounding tissues and the horizontal yellow line is an indication of the blood temperature (37°C). Two regions exist within the brain that lead to contrasting temperature behaviors.

The majority of the brain tissue is at a resting-state temperature that is less than the blood temperature (region 1). For voxels within this region, a behavior like that shown in Fig. 2.3(d) is to be expected. The primary contribution to an increase in the BOLD response is an increase in local blood flow. Since the blood temperature is cooler than the tissue temperature, blood flow removes heat from the tissue thereby lowering the temperature. Single-voxel models are able to account for this result because their assumptions about the location of a voxel are consistent with being located within this region.

The second region is comprised of a thin (4–6 mm) layer of brain tissue that is closest to the surface of the head. As a result of its proximity to the surface of the head, conductive heat lost to the air puts the resting-state temperature of voxels in this region below the
Figure 2.3  Temperature changes using simulated BOLD signals. (a) Slice of the head (y = -12) with indicators of the locations for parts (b)-(d). (b) Equilibrium temperature along a line through the head. Red lines indicate the brain boundary and the gold line indicates the blood temperature (37°C) used for calculations. Inside the brain, a 4-6 mm thick shell is created where the equilibrium temperature is less than the blood temperature. Within this shell, (c) the temperature rises with increased brain activity while (d) tissue deeper in the brain experiences the opposite effect.
arterial blood temperature. As a result, when there is an increase in blood flow (increase in BOLD), the warmer blood will increase the voxel temperature (Fig. 2.3(c)). A separate study of brain temperature using a full-head model found this region to be as thick as 1 cm [41]. Since single-voxel models approximate voxel conditions, they are unable to account for this region of tissue.

Conduction is a slow process, so over shorter time scales (less than ~10 minutes), conduction will contribute very little to the temperature change from a change in brain activity. However, conduction plays an important role in determining the resting-state temperature.

The primary advantage with this model is that it accounts for the contribution of all of the voxels when determining the temperature, thus the direction of the temperature change depends on how far away from the surface of the head the voxel is. For voxels within a 4–6 mm shell near the surface of the brain, the temperature increases with increased activity (Fig. 2.3(c)) while voxels deeper within the brain experience the opposite change (Fig. 2.3(d)).

### 2.3.2 Using Experimental BOLD Data

Data from a previous fMRI study [39] was used to study the characteristics of temperature changes in a typical experiment. All participants in this experiment were right handed and between the ages of 23 and 27 years old. Signed informed consent was collected from each one prior to participating in the study. Institutional Review Boards of Emory University and Georgia State University approved this experiment. Twelve participants were asked to tap their right index fingers with rhythms of varying complexity for 320s.

This task resulted in a strong BOLD response in the motor cortex (Fig. 2.4). The experiment included 20s of rest at the beginning and end of the tapping periods. Here, the resting state response level is calculated for each voxel by averaging across 40s of resting-state fMRI data. Using equations Eqs. (2.9), (2.15) and (2.16), the time-dependent change in blood flow and metabolism can be determined for each voxel. Finally, these values are used in conjunction with Eq. (2.4) to find the change in temperature throughout the brain. In this task, a temperature increase of approximately 0.02°C was observed in the motor
Figure 2.4  Temperature calculated from a voxel within the motor cortex. (a) A slice (x = -44) showing the motor cortex warming during a finger-tapping task. (b) Temperature at a voxel within the motor cortex (-44, -24, 60) with standard error indicated by blue error bars (Arrows indicate task onset and conclusion, N=24).
cortex (Fig. 2.4). This value is well within the range of temperature changes observed in experimental measurements [10, 11, 12, 13, 14].

The increase rather than decrease in temperature in the motor cortex during a functional activity is consistent with the idea that the temperature of the blood in the capillaries is slightly greater than the baseline tissue temperature in superficial cortical regions; however, single-voxel models would predict the opposite effect.
The best method for measuring brain temperature is to use a thermocouple probe placed in direct contact with the tissue. Experimental measurements of brain temperature have achieved a precision as small as 0.0003°C using this method [10]. However, this method can not be used in humans without damaging the tissue. An optical method would be ideal for non-invasive measurements. Presently, there does not exist a method for accurately measuring the temperature of brain tissues optically. However, other optical measurements methods could be used in conjunction with a temperature model (such as the one proposed here) to calculate the temperature. The possible application of functional Near-Infrared Spectroscopy (fNIRS) and its possible use in brain temperature calculations is discussed along with the possibilities and limitations of a direct measurement technique such as thermal imaging.

3.1 Functional Near-Infrared fNIR Spectroscopy

As discussed in chapter 1, changes in tissue activity can be detected by measuring the change in blood oxygenation levels. Functional Magnetic Resonance Imaging (fMRI) is one technique among several for measuring tissue oxygenation (the BOLD signal).

Blood oxygenation can be determined by measuring the relative concentrations of oxyhe-

<table>
<thead>
<tr>
<th></th>
<th>fMRI</th>
<th>fNIR</th>
</tr>
</thead>
<tbody>
<tr>
<td>Spatial Resolution</td>
<td>8–27 mm³</td>
<td>≈ 1–10 cm³</td>
</tr>
<tr>
<td>Temporal Resolution</td>
<td>1–2 s</td>
<td>≈ 10⁻³ s</td>
</tr>
<tr>
<td>Measurement Parameter</td>
<td>blood volume, flow, and O₂</td>
<td>oxyHb and deoxyHb concen-</td>
</tr>
<tr>
<td></td>
<td>metabolism</td>
<td>trations</td>
</tr>
<tr>
<td>Motion</td>
<td>Must Remain Stationary</td>
<td>Small movements OK</td>
</tr>
<tr>
<td>Penetration</td>
<td>Whole-head</td>
<td>outer 2–4 mm of brain tissue</td>
</tr>
</tbody>
</table>

Table 3.1 Comparison of the capabilities and limitations of fMRI and fNIR techniques. Compiled from Bunce et al. [44], Elliott [45].
moglobin (oxyHb) and deoxyhemoglobin (deoxyHb) [6, 7, 8]. Since oxyHb and deoxyHb have different absorption spectra as shown in Fig. 3.1. These differences are possible to detect through optical techniques. Functional Near-Infrared Spectroscopy is a technique which utilizes two or more spectral bands in order to determine blood oxygenation. fNIRS has a high (millisecond) temporal resolution and a low (∼1 cm$^3$) spatial resolution compared to fMRI (as low as 1 mm$^3$). Also, fNIRS is limited to only imaging the outer cortex (2–4 mm) [44]. A comparison of fMRI and fNIR is presented in Table 3.1.

fNIRS works by utilizing an array of near-infrared detectors and emitters (typically spaced 2–3 cm apart) placed in contact with the skin [46, 47]. A schematic of a typical fNIRS array setup is shown in Fig. 3.2. Each dashed line is a detection path. By illuminating the emitters
Figure 3.2 A Sample arrangement of detectors and emitters in a typical 16-channel fNIRS setup (based on Izzetoglu et al. [47]). Light coming from emitters (stars) is detected by the detectors (circles) set at a distance L away.

sequentially, it is possible to have 16 detection channels using the setup shown. The exact spacing between the emitters and detectors determines the depth the light is detected from. As shown in Fig. 3.3, the closer the spacing, the higher the resolution but at the expense of lower penetration. Conversely, in order to detect light passing through deeper tissue, a wider spacing is used which reduces the resolution. Systems use either two [46, 48, 49] or three [50] wavelengths selected based on differences in the absorption of oxyHb and deoxyHb. The exact wavelengths used vary, but all lie within an optical window between 700–1000 nm [46] where the near-infrared photon absorption in the tissue is low (Fig. 3.1).

Three techniques are used to illuminate the tissue: (i) time domain (or time resolved spectroscopy, TRS), (ii) frequency domain and, (iii) continuous wave illumination [47]. In TRS, short pulses of light are incident on the tissue and the temporal distribution of photons in measured. In frequency domain spectroscopy, the amplitude of the incident light is modulated at a high frequency (10–100 MHz) and the phase shift and amplitude decay of the detected light is compared to the incident light [52]. In continuous wave illumination, the incident light is not modulated so the detected light can only be compared for amplitude attenuation [47].

All of the techniques use the Beer-Lambert Law [53]

\[ I = I_0 e^{-\alpha(\lambda)x} \]  \hspace{1cm} (3.1)
modified to isolate the individual contributions from oxyHb and deoxyHb [42]:

\[ I = GI_0e^{-\left(\alpha_{\text{oxyHb}}C_{\text{oxyHb}}+\alpha_{\text{deoxyHb}}C_{\text{deoxyHb}}\right)l} \]  

(3.2)

where \( G \) is a factor to adjust for the measurement geometry, \( I_0 \) is in the incident light intensity, \( \alpha_{\text{oxyHb}} \) and \( \alpha_{\text{deoxyHb}} \) are the molar extinction coefficients for oxyHb and deoxyHb, \( C_{\text{oxyHb}} \) and \( C_{\text{deoxyHb}} \) are the chromophore concentrations for oxyHb and deoxyHb, and \( l \) is the path length [47]. By comparing a baseline measurement \( (I_b) \) with a new measurement \( (I) \),
the optical density can be determined [47].

\[ \Delta OD = \log \frac{I_b}{I} = \alpha_{\text{deoxyHb}} \Delta C_{\text{deoxyHb}} + \alpha_{\text{oxyHb}} \Delta C_{\text{oxyHb}} \]  

(3.3)

As discussed in Izzetoglu et al. [47], at least two wavelengths are utilized in the spectral window (700–1000 nm) in order to determine the change in concentration of chromophores \( \Delta C_{\text{deoxyHb}} \) and \( \Delta C_{\text{oxyHb}} \). With these values, the oxygenation and total blood volume can be determined:

\[
\begin{align*}
\text{Oxygenation} &= \Delta C_{\text{HBO}_2} - \Delta C_{\text{HB}} \\
\text{Blood Volume} &= \Delta C_{\text{HBO}_2} + \Delta C_{\text{HB}}
\end{align*}
\]  

(3.4)

Using this method to experimentally measure the blood oxygenation while measuring the fMRI BOLD response could be used to refine the present model for calculating the metabolism and blood flow from the BOLD response.

While fNIRS does not provide spatially-precise measurements as fMRI, it should be possible to modify the existing model for calculating temperature from the BOLD response to use fNIR data. This would be advantageous because fNIRS systems are cheaper and less disruptive than fMRI systems, meaning they can be used with a wider range of patients (children and the elderly). For this reason, developing a model which uses fNIRS data should be considered in future research.

### 3.2 Thermal Imaging

The primary challenge in brain temperature research is performing brain temperature experimental measurements. Since it is non-invasive, thermal imaging is appealing as a possible replacement for damaging thermocouple probes. Unfortunately, this technique is limited by the high absorption of mid-infrared photons by water.
Light absorption by a material is modeled using the Beer-Lambert law

\[ I = I_0 e^{-\alpha(\lambda)x} \]  

(3.5)

where \( I \) is the intensity at a depth \( x \) remaining from light with an incident intensity \( I_0 \) in a material with absorption coefficient \( \alpha \). The point at which the intensity has decayed to \( 1/e \) (about 37%) of the incident intensity is called the penetration depth, \( \delta_p \)

\[ \delta_p = \frac{1}{\alpha(\lambda)} \]  

(3.6)

This equation can be used along with the black-body spectrum at tissue temperatures (Fig. 3.4) we can estimate the penetration depth of mid-infrared photons passing through water.

Wien’s Displacement Law is a solution to Planck’s law for the peak light emission wavelength:

\[ \lambda_{max} = \frac{b}{T} \]  

(3.7)

where \( b \) is Wien’s displacement constant and \( T \) is the temperature in kelvin. For \( T = 310 \) K \( (T = 37^\circ \text{C}) \), Wien’s law yields a peak black-body emission wavelength of 9.347 652 \( \mu \text{m} \). A physiologically reasonable temperature change to expect from stimulation is on the order of 0.01\(^{\circ}\)C which corresponds to a new peak wavelength of 9.347 350 \( \mu \text{m} \) \((T=310.01 \text{ K})\) or a shift of 0.302 nm.

The values of the absorption coefficient and the penetration depth of photons in water is shown in Fig. 3.5. Looking at around 9.3 \( \mu \text{m} \), the absorption coefficient is approximately 700 cm\(^{-1}\) which corresponds to a penetration depth of approximately 14 \( \mu \text{m} \). This depth is roughly three orders of magnitude smaller than the distance from the surface of the brain to
Figure 3.4  (a) Black-body spectrum at 250, 310 and 350 K calculated using Planck’s Law. The black dashed line traces the peak in the spectrum as temperature changes. As the temperature increases, differences in temperature translate to smaller shifts in peak wavelength compared to cooler temperatures. (b) A comparison of the black-body spectrum at 310 K and 310.025 K. This is the shift in local temperature that would be expected under strong stimulation.
Figure 3.5  The absorptions spectra of water from UV to far-infrared. Modified from Hale and Querry [54].

the surface of the head. Further, all photons emitted as blackbody radiation (ranging from 3 µm to over 30 µm) have a penetration depth of less than 100 microns. Thus, a thermal imaging camera is unable to image photons coming from the brain.

When thermal imaging is used, the photons collected come from the skin of the head rather than from any deeper tissues, thus it is not a viable form of brain activity detection unless direct line of sight to the brain is available (such as in an open skull surgery). The noise-equivalent temperature difference (NETD) of currently available cameras is greater than 14 mK [55, 56] or 7 mK [57] for a camera which is not commercially available, so it would be limited to only the most extreme of excitations even if line of site to the brain is available. As a comparison, the finger-tapping task discussed in the results section (section 2.3.2) only
induced a peak temperature change of 25 mK after tapping for about 170 seconds. Detection of this activity would be at the limits of a thermal imaging camera.

While its applications to detecting brain activity are limited, thermal cameras could be useful in the operating room. It has been found that inducing mild hypothermia in patients being treated for cerebral ischemia improves the clinical outcome [20]. The same treatment has been shown to improve the outcome of patients who have experienced a stroke [22], and even in patients with severe head injuries [19]. The temperature of the brain is currently inferred from the core body temperature (which is monitored via an invasive thermistor catheter). If it is possible to directly image the brain (i.e. during surgery) then the hypothermia treatment can be better monitored through a thermal imaging camera. This would be especially useful since conductive and radiative heat loss to the air from an exposed brain could reduce how tightly the brain temperature is regulated by the arterial blood temperature. Since the tissue will be directly exposed to the surrounding air, Eq. (2.1) would need to include a term for the radiative heat loss:

\[
C_{\text{tissue}} \frac{dT(t)}{dt} = \ldots + \frac{A\sigma T^4}{\rho_{gm}V}
\]  

(3.8)

After rearranging to solve for \[
\frac{dT}{dt}
\] and substituting values in, it is found that the change in temperature is approximately 0.07 K/s:

\[
\frac{dT}{dt} = \frac{A\sigma T^4}{\rho_{gm}VC_{\text{tissue}}}
\]

\[
\begin{align*}
&= \frac{1}{6} \left( 6 \times 4 \times 10^{-6} \text{ m}^2 \right) \left( 5.6704 \times 10^{-8} \text{ J m}^{-2} \text{ K}^{-4} \right) \left( 310 \text{ K} \right)^4 \\
&= \frac{1}{6} \left( 1035 \times 10^{-3} \text{ kg m}^{-1} \right) \left( 8 \times 10^{-9} \text{ m}^3 \right) \left( 3.664 \times 10^{-3} \text{ J kg}^{-1} \text{ K}^{-1} \right) \\
&\approx 0.0690454 \frac{\text{K}}{\text{s}}
\end{align*}
\]  

(3.9)

where \(A\) and \(V\) are the surface area and volume of the voxel, \(\sigma\) is the Stefan-Boltzmann constant and \(\rho_{gm}\) is the density of gray matter. The factor 1/6 is there because only one face of the voxel is exposed to air. Radiation passing through the other faces will be reabsorbed
by the tissue (Fig. 3.5).

Optical detectors face many challenges working with biological tissue, the worst being infrared light absorption by water. fNIRS works within an optical window in the water absorption in order to measure changes in blood oxygenation, while thermal imaging is limited to measuring the temperature of tissue it has direct line of sight with because of the high absorption of water in the operating window. Despite their limitations, both of these techniques could be used in future studies to improve our understanding of brain temperature dynamics.
4 Conclusion

It has been shown that by considering the entire head within the model, brain temperature can be reliably calculated from non-invasive fMRI measurements. Experimental measurements of activity-induced brain temperature changes have shown that a simple relationship does not exist [10, 11, 12, 13, 14]. Single-voxel brain temperature modeling efforts predict that an increase in brain activity will induce a decrease in temperature. This one-dimensional perspective does not account for the spatial distribution of heat throughout the head like a multi-voxel approach.

Our model of brain temperature changes is able to account for the variability found in experimental brain temperature measurements. This is accomplished by modeling heat dynamics throughout the entire head rather than reducing the model to one ROI. It was found that the variability in experiment measurements is most likely due to differences in resting state temperatures throughout the brain. Since each voxel is at a slightly different temperature, the same change in the BOLD response may result in different changes in temperature. Additionally, it was found through the model that a thin (4–6 mm) region of outer cortical tissue is at a resting temperature below the blood temperature. In this region, an increase in brain activity (inducing an increase in CBF) will warm the tissue. Thus, with the same BOLD response, tissue may either be warmed or cooled depending on it’s proximity to the surface of the head.

The biggest shortcoming of our model is that we are unable to independently compare our calculations with experimental measurements of temperature and BOLD response. It was not possible for us to do this because there is currently not a method for non-invasively measuring temperature independent of an fMRI. An improvement to the model could also be gained by a more accurate method of CMRO$_2$ and CBF calculations from the BOLD response. The current method uses empirically fit formulas, so the accuracy is limited by
the data used for the fitting. A model that does not rely on experimental data would be ideal. The calculations could also be improved by segmenting the head into more tissue types. We used six tissue types, but the use of more would further improve the calculations since each tissue type has different physiological parameters (thermal conduction, baseline heat production, etc.). A separate line of research that could be pursued would be a model for calculating brain temperature changes from fNIRS data. Both fNIRS and fMRI BOLD response detect changes in local tissue oxygenation, so it should be possible to adapt our model to use fNIRS data. If such a model existed, calculations from it and our model could be compared to refine both models.

Although it is expected that the contribution would be negligible [58], our model does not take into account the effects of perspiration. It would likely not affect the change in temperature greatly because it takes place a couple of centimeters away from brain tissue. Another physiological affect not account for is temperature regulation by the pre-optic nucleus of the anterior hypothalamus [17]. It is responsible for balancing heat production and dissipation [59] and if the model were applied to cases where extreme brain temperatures are created then it would be important to account for how this would react.

How human brain temperature is affected by changes in local brain activity is not well understood because the changes are small and current experimental measurement techniques may require invasive procedures. Models such as the one proposed here allow for brain temperature to be understood through non-invasive measurements such as the fMRI BOLD response.
References


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Appendix A  Code

The following sections include the code used. It was written for Matlab R2011b and requires SPM8 to run. Additionally, it is recommended that you have at least 4 GB of RAM in order to work with the large datasets that are produced. For information about how to visualize the data produced, see appendix B. All of the code is available through the temptools github page (https://github.com/greggroth/temptools). Additionally, many of the tasks can be completed using the temptools gui (Figs. (A.1) - (A.4)) which can be invoked by running temptools at the Matlab command prompt (make sure the temptools directory and subdirectories have been added to the Matlab path). The procedure used is explained in section 2.2 and a graphical representation is available in Fig. 2.1.
Figure A.1  The main window of temptools. From here, you can go through the calculation steps and launch the visualization tool.
Figure A.2  This is the interface for calculating the equilibrium temperature (method explained in appendix A.3) under certain conditions.
Figure A.3  The interface for calculating temperature changes when blood flow and metabolism are time dependent. This can be achieved by either loading metabolism and blood flow datasets or by using generated activity.
Figure A.4  Visualize your data using the temptools visualization window. This loads all of the required data and launches a slice browser or tsliceplot (see appendix B for more details).
A.1 Creating the Head Matrix

Before any calculations can be done, a matrix containing tissue-specific parameters must be created. First, a T1 contrast image should be segmented using SPM8 (http://www.fil.ion.ucl.ac.uk/spm/software/spm8/). For ease of consistency, the one provided by SPM8 in ./canonical/ is best to use. Using SPM’s “New Segmentation” algorithm will segment the image into five different tissue types (gray matter, white matter, cerebral spinal fluid, soft tissue and bone). Once this is complete, run ImportSegmentedT1() within this directory and it will return a matrix that has been populated with the tissue-specific parameters required for accurate temperature calculations. The functions fillAir() (A.1.2), fillHoles() (A.1.3), build_skin() (A.1.4) and repair_headdata() (A.1.5) are functions required by BulkImportNII(). More information about this procedure is in section 2.2.1.

A.1.1 ImportSegmentedT1()

```matlab
function [ total ] = ImportSegmentedT1(varargin)

% ImportSegmentedT1 Import NII files from a directory
% Must be run within the directory containing the files
%
% Output: head data as single with variables stored in the 4th dimension.
%
% Author: Greggory Rothmeier (greggroth@gmail.com)
% Georgia State University
% Created: 5/31/11

statusbar = waitbar(0,'Initializing');

if size(varargin) == 1
    oldFolder = cd(varargin{1});
```
end

% = Tissue Parameters =
% Each tissue type is assigned an integer index (i.e. gray matter -> 11)
% such that tissue-specific parameters can be found by looking at
% that element within the corresponding storage matrix
% (i.e. QmSTORE(11) -> gray matter Qm)

% Parameters taken from Colins, 2004

tisorder = [11 15 5 13 3]; % Using: [GM WM CSF Muscle Bone]

QmSTORE = [0 0 26.1 11600 0 26.1 697 0 0 302 15575 0 697 1100 5192];
cSTORE = [1006 4600 2110 3640 3800 1300 3720 3000 4200 2300 3680
          3500 3720 3150 3600];
rhoSTORE = [1.3 1057 1080 1035.5 1007 1850 1126 1076 1009 916
           1035.5 1151 1041 1100 1027.4];
kSTORE = [0.026 0.51 0.65 0.534 0.5 0.65 0.527 0.4 0.594 0.25 0.565
          0.4975 0.4975 .342 .503];
wSTORE = [0 1000 3 45.2 0 1.35 40 0 0 2.8 67.1 3.8 3.8 12 23.7];

% = Import the pre-segmented T1 files =
% =====================================
The T1 contrast image should be segmented using SPM8.

This loop needs to complete before the next one can begin.

Import all of the data and store as 'cdat1', 'cdat2', etc.

for i = 1:5
    eval(strcat('dat', num2str(i), ' = loadNII(''rc', num2str(i), singlesubj_T1.nii'');'))
    eval(strcat('out', num2str(i), ' = zeros(cat(2, size(dat', num2str(i), ')), 7)));'))
end

% ============================
% = Populate the head matrix =
% ============================
% For each data file, it fills in the data from the data storage arrays for that particular type of tissue. It picks which ever tissue is the most likely candidate for that voxel based on the segmented data

% PROBLEM: It returns 0 (later filled with air) if there is equal probability of a voxel being two or more different types of tissue.
% SOLVED BY fillHoles()

for i = 1:5
    % Preallocate
    holder = zeros(cat(2, size(dat1), 7), 'single');
    mask = zeros(size(dat1));
final = zeros(size(holder), 'single');

% Create a mask that indicates whether it is the mostly likely tissue type
guide = [1 2 3 4 5 1 2 3 4 5]; % This guides it through the data correctly
eval(strcat('mask = (dat', num2str(i), '>dat', num2str(guide(i+1)), ' & (dat', num2str(i), '>dat', num2str(guide(i+2)), ' & (dat', num2str(i), '>dat', num2str(guide(i+3)), ' & (dat', num2str(i), '>dat', num2str(guide(i+4)), ') & (dat', num2str(i), ' ~=0);')))

% move structure data to new matrix
holder(:,:,1,:) = mask;
% get indicies of tissues
a = find(holder(:,:,1,:) == 1);
% gets coordinates from index
[x y z t] = ind2sub(size(holder), a);

% go to each tissue point and store the info
for j = 1:length(a)
    final(x(j), y(j), z(j), :) = [tisorder(i) 0 QmSTORE(tisorder(i)) cSTORE(tisorder(i)) rhoSTORE(tisorder(i)) kSTORE(tisorder(i)) wSTORE(tisorder(i))];
end

% Saves the result to a unique output variable (out1, out2, etc)
eval(strcat('out', num2str(i), '= final;'))
clearvars a x y z t holder final;
waitbar(i/6,statusbar,sprintf(['File ',num2str(i),' Import Compete']));
end

% The filleAir() function checks for any voxels which were not
% assigned a tissue type and fills them in with air
almostthere = fillAir(out1+out2+out3+out4+out5);
% The fillHoles() function corrects for a voxel having two
% equally-probable tissue types
total = single(buildskin(fillHoles(dat1,dat2,dat3,dat4,dat5,almostthere)));
waitbar(1,statusbar,'Saving Data')

cd(oldFolder);
close(statusbar);
end

A.1.2 filleAir()

function [ output ] = fillAir( tissue )
% filleAir() fills gaps in data with air
% Once you import all of the data using loadNII(), run it though
% this to fill in the remaining spaces with air.

airdata = [1 0 0 1006 1.3 0.026 0];

% Picks out air spots
a = find(tissue(:,:,:,:1) == 0);
[x y z t] = ind2sub(size(tissue),a);
for i = 1:length(a)
    tissue(x(i),y(i),z(i),:) = airdata;
end

output = tissue;
end

A.1.3 fillHoles()

function [ out_head ] = fillHoles( in1,in2,in3,in4,in5,headin)
% fillHoles() checks for misassigned voxels
%
% Solves an issue where a voxel with two equally probable tissue
% types resulted in being assigned as air. This checks for air
% voxels that are surrounded by tissue and decides a tissue it
% it would be best suited as
%
% I only need the tissue indices so this makes things easier down
% the line
head = squeeze(headin(:,:,,:));

% Data Storage
QmSTORE = [0 0 26.1 11600 0 26.1 697 0 0 302 15575 0 697 1100
5192];
cSTORE = [1006 4600 2110 3640 3800 1300 3720 3000 4200 2300 3680
3500 3720 3150 3600];
rhoSTORE = [1.3 1057 1080 1035.5 1007 1850 1126 1076 1009 916
1035.5 1151 1041 1100 1027.4];
kSTORE = [0.026 0.51 0.65 0.534 0.5 0.65 0.527 0.4 0.594 0.25 0.565
          0.4975 0.4975 .342 .503];
wSTORE = [0 1000 3 45.2 0 1.35 40 0 0 2.8 67.1 3.8 3.8 12 23.7];

%% Get locations of holes
% Where two tissue types have the same probability
idx1 = (in1 == in2 | in1 == in3 | in1 == in4 | in1 == in5) & logical(in1);
idx2 = (in1 == in2 | in2 == in3 | in2 == in4 | in2 == in5) & logical(in2);
idx3 = (in1 == in3 | in2 == in3 | in3 == in4 | in3 == in5) & logical(in3);
idx4 = (in1 == in4 | in2 == in4 | in3 == in4 | in4 == in5) & logical(in4);
idx5 = (in1 == in5 | in2 == in5 | in3 == in5 | in4 == in5) & logical(in5);

% This array will have a zero anywhere there were two or more
% common elements between any of the five arrays.
idx = idx1 | idx2 | idx3 | idx4 | idx5;

[xmax ymax zmax] = size(in1);
[x y z] = ind2sub(size(in1),find(idx)); % get x, y and z coordinates of the holes

for i = 1:length(x) % go to each hole and do work
    if (x(i)~=1) && (y(i)~=1) && (z(i)~=1) && (x(i)~=xmax) && (y(i)~=ymax)
        && (z(i)~=zmax) && (headin(x(i),y(i),z(i),1)==1) % keeps away from the edge and only looks at voxels that were assigned air
[commonesttissue nouse secondbest] = mode([head(x(i)+1,y(i),z(i))
,head(x(i)-1,y(i),z(i)) head(x(i),y(i)+1,z(i)) head
(x(i),y(i)-1,z(i)) head(x(i),y(i),z(i)+1) head(x(i),y(i),
z(i)-1)])

% if air and something else are equally common, it'll
choose air. This forces it to pick the tissue if
possible.
if commonesttissue == 1 && length(secondbest{1})>=2
    commonesttissue = secondbest{1}(2);
end
headin(x(i),y(i),z(i),:) = [commonesttissue 0 QmSTORE(
    commonesttissue) cSTORE(commonesttissue) rhoSTORE(
    commonesttissue) kSTORE(commonesttissue) wSTORE(
    commonesttissue)];
end
end
end
out_head = headin;
end

A.1.4 build_skin()

function [ head_out ] = build_skin( head_in )
% build_skin() Creates a layer of skin around the head
%
% This will check all voxels that were previously labeled
% as soft tissue and checks if it has a neighbor which is air.
% If so, then it is reassigned as skin.
if ndims(head_in)==4
    head_in = head_in(:,:,1);
end

% Get a list of all voxels labeled as muscle
muscle_voxels = find(head_in==13);

% Go through each of them and check for neighboring air voxels
for i=1:length(muscle_voxels)
    [x y z] = ind2sub(size(head_in), muscle_voxels(i));
    % makes sure we’re not at a voxel at the boundary of the dataset
    if (x~=1) && (x~=size(head_in,1)) && (y~=1) && (y~=size(head_in,2)) && (z~=1) && (z~=size(head_in,3))
        % Looks for neighboring voxels that are air
        if ((head_in(x+1,y,z)==1) || (head_in(x-1,y,z)==1) || (head_in(x+1,y-1,z)==1) || (head_in(x,y+1,z)==1) || (head_in(x,y,z+1)==1) || (head_in(x,y,z-1)==1))
            head_in(x,y,z) = 14;
        end
    end
end

head_out = repair_headdata(head_in);

A.1.5 repair_headdata()

This function will go through the dataset and make sure the tissue-specific parameters are correct for the tissue type assigned for that voxel. fillAir(), fillHoles() and build_skin() all
correct mislabeled voxels, but they only correct the tissue assignment. After using any of these functions, the data must be passed through repair_headdata to update the stored parameters.

```matlab
function [ head_out ] = repair_headdata( head_in )
% repair_headdata repopulates the headdata matrix
% If any changes are made to the index column in the headdata matrix, use this function to repopulate and correct the parameter values before running any other functions.
% head_in can be either 3 or 4 dimensions

% ===============
% = Parameter Storage =
% ===============

QmSTORE = [0 0 26.1 11600 0 26.1 697 0 0 302 15575 0 500 1100
          5192];
cSTORE = [1006 4600 2110 3640 3800 1300 3720 3000 4200 2300 3680
            3500 3010 3150 3600];
rhoSTORE = [1.3 1057 1080 1035.5 1007 1850 1126 1076 1009 916
            1035.5 1151 978.5 1100 1027.4];
kSTORE = [0.026 0.51 0.65 0.534 0.5 0.65 0.527 0.4 0.594 0.25 0.565
            0.4975 0.3738 .342 .503];
wSTORE = [0 1000 3 45.2 0 1.35 40 0 0 2.8 67.1 3.8 3.3 12 23.7];

if ndims(head_in)==4
    head_in = head_in(:,:,1);
end
```
% Reassign the parameter values

head_out = cat(4, head_in, zeros(size(head_in)), QmSTORE(head_in),
    cSTORE(head_in), rhoSTORE(head_in), kSTORE(head_in), wSTORE(head_in));

end
A.2 Loading the fMRI Data

The following sections details the processing required to convert the BOLD data (in NIFTI format) to metabolism and blood flow time-courses that can then be used to calculate temperature.

A.2.1 sample_bold_import()

The following code automates the procedure of processing and doing all the calculations on the dataset reported in Dhamala et al. [39]. It’s is written for my data on my machine, but it can be used to gain a better understanding of the procedure. For a conceptual explanation, see section 2.2.3.

```matlab
% %================================================================
% % How to process preprocessed BOLD data to calculate temperature
% %================================================================

% This Matlab script was used to automate the process of using
% BOLD data stored in NIFTI (*.nii) format to calculate temperature
% changes. The particulars of the code may be specific to this
% case, but the procedure should be the same when doing these
% calculations on other datasets. All required functions are
% included as an attachment to my thesis and are available on my
% github (https://github.com/greggroth/tempcalc)

cd('/Users/Greggory/Documents/Data/fmri_rhythmic_tapping01/NIFTI')
directories = dir('*01');

%% Move coregistered files to new Directory
for i = 1:length(directories)

```
```matlab

dir_name = directories(i).name;
main_path = cd( [dir_name filesep dir_name '_NIFTI_1'] );
mkdir 'Coregistered'
movefile('r*.nii','Coregistered')
main_path = cd( [dir_name filesep dir_name '_NIFTI_2'] );
mkdir 'Coregistered'
movefile('r*.nii','Coregistered')
cd(main_path)
end

%% Calculate Rest State
disp('Calculating Rest State')
for i = 1:length(directories)
    dir_name = directories(i).name;
    avg_NII_rest([dir_name filesep dir_name '_NIFTI_1' filesep 'Coregistered']);
    avg_NII_rest([dir_name filesep dir_name '_NIFTI_2' filesep 'Coregistered']);
end

%% Normalize to Rest and Mask
disp('Normalize to Rest and Mask')
for i = 1:length(directories)
    dir_name = directories(i).name;
    avg_NII_normalize([dir_name filesep dir_name '_NIFTI_1' filesep 'Coregistered'], fullfile(dir_name, [dir_name '_NIFTI_1'], 'Coregistered', 'RestState', 'RestStateAvg.nii'), 'fullBrainMask.nii');
```
avg_NII_normalize(fullfile(dir_name, [dir_name '_NIFTI_2'], 'Coregistered'), fullfile(dir_name, [dir_name '_NIFTI_2'], 'Coregistered'), 'RestState', 'RestStateAvg.nii'),
fullBrainMask.nii');

%% Calculate metabolism and blood flow change

disp('Calculate metabolism and blood flow change')

for i = 1:length(directories)
    dir_1 = [directories(i).name filesep directories(i).name '_NIFTI_1' filesep 'Coregistered' filesep 'Normalized_to_rest']
    dir_2 = [directories(i).name filesep directories(i).name '_NIFTI_2' filesep 'Coregistered' filesep 'Normalized_to_rest']
    BOLDtoMF(dir_1);
    BOLDtoMF(dir_2);
end

%% Calculate the change in temperature based on metabolism and blood flow

% load('equil.mat'); % equillibriumT
% load('tt_headdata.mat'); % headdata
mask = loadNII('fullBrainMask.nii');

for i = 1:length(directories)
disp(['int2str(i) ' -1 started'])
tic

% Part I
actResult.dat = tempCalcDynMF(headdata, 37, 24, 720, 360,
equilibriumT, ...
fullfile(directories(i).name,[directories(i).name ' _NIFTI_1 '
'],,'Coregistered', 'Normalized_to_rest', 'Output_18-Sep -2011', 'm.mat'), ...
fullfile(directories(i).name,[directories(i).name ' _NIFTI_1 '
'],,'Coregistered', 'Normalized_to_rest', 'Output_18-Sep -2011', 'f.mat'), ...
4, mask);

% Store the parameters used for the calculations for reference
in the future
[c lmax] = max(actResult.dat(:));
[likelymax x y z] = ind2sub(size(actResult.dat),lmax);
actResult.likelymaxslice = round(likelymax/2);
actResult.bloodT = 37;
actResult.airT = 24;
actResult.tmax = 360;
actResult.stepf = 2;
actResult.savestepf = 4;
actResult.metabandflowdata = 'From Dataset';
save(fullfile(directories(i).name,[directories(i).name ' 
    _NIFTI_1'],,'Coregistered', 'Normalized_to_rest', 'Output_18-Sep-2011','tt_act_res.mat'), 'actResult');
old = cd([directories(i).name,filesep,[directories(i).name ' 
    _NIFTI_1'],filesep,'Coregistered', filesep,' Normalized_to_rest', filesep,'Output_18-Sep-2011']);
writeT_to_nii(actResult, equilibriumT, exp_nii);

cd(old)
clear actResult

% Part II
disp([int2str(i) ' -2 started'])
actResult.dat = tempCalcDynMF(headdata, 37, 24, 720, 360,
   equilibriumT, ...
   fullfile(directories(i).name,[directories(i).name '_NIFTI_2
   ', 'Coregistered', 'Normalized_to_rest', 'Output_18-Sep
   -2011', 'm.mat'), ...
   fullfile(directories(i).name,[directories(i).name '_NIFTI_2
   ', 'Coregistered', 'Normalized_to_rest', 'Output_18-Sep
   -2011', 'f.mat'), ...
   4, mask);
   [c lmax] = max(actResult.dat(:));
   [likelymax x y z] = ind2sub(size(actResult.dat),lmax);
actResult.likelymaxslice = round(likelymax/2);
actResult.bloodT = 37;
actResult.airT = 24;
actResult.tmax = 360;
actResult.stepf = 2;
actResult.savestepf = 4;
actResult.metabandflowdata = 'From Dataset';
save(fullfile(directories(i).name,[directories(i).name '_NIFTI_2','Coregistered', 'Normalized_to_rest', 'Output_18-Sep-2011','tt_act_res.mat'), 'actResult');

old = cd([directories(i).name,filesep,[directories(i).name '_NIFTI_2'],filesep,'Coregistered', filesep,'Normalized_to_rest', filesep,'Output_18-Sep-2011']);
writeT_to_nii(actResult, equilibriumT, exp_nii);
cd(old)
clear actResult
disp([int2str(i) ' finished in ' num2str(toc)])
end

A.2.2 avg_NII_rest()

function [] = avg_NII_rest( varargin )

% Collects datasets which are part of the
% resting state and averages them together to
% give a resting-state image
%
% THIS MUST BE EDITED TO WORK
% This is written for my data and you should read
% and understand what it is doing before you use it.
% It will almost certainly require some editing
% to select the right range of data.

%% Setup
switch length(varargin)
    case 0
        fold_name = uigetdir;
        if ~fold_name  % Cancel Button
            return
        end
    case 1
        fold_name = varargin{1};
    otherwise
end
% Go to the folder containing the files
oldfold = cd(fold_name);

file_list = dir('*.nii');

% Select resting state images
% (first and last 10 steps in my case).
% EDIT THIS TO FIT YOUR CASE
file_list = file_list([1:10 170:180]);
file_count = length(file_list);

% Cell array to store all of the datasets in.
datHolder = cell(file_count,1);

statusbar = waitbar(0,'Initializing');

for j = 1:file_count
    try
        waitbar(j/file_count,statusbar,sprintf('%d%%',round((j/
            file_count)*100)));
        catch err
            return
        end
        fi = load_nii(file_list(j).name);
        datHolder{j} = fi.img;
    end

% Calculate the mean
ymax = size(datHolder{1},2);
zmax = size(datHolder{1},3);
output = zeros(size(datHolder{1}));

for i=1:ymax
    try
        waitbar(i/ymax,statusbar,sprintf('%d%%',round((i/ymax)*100)));
    catch err
        return
    end
    for k=1:zmax
        excStr = cell(length(datHolder),1);
        for l=1:length(datHolder)
            excStr{l} = [' datHolder{' int2str(l) '}(:,' int2str(i) 
            ',' int2str(k) ')''
            ];
        end
        comb = eval(['cat(1 cell2mat(excStr) ')']);
        output(:,i,k) = mean(comb);
    end
end

close(statusbar)

fi.img = output;
mkdir('RestState')
save_nii(fi,fullfile('RestState','RestStateAvg.nii'));

cd(oldfold)
end
function [   ] = avg_NII_normalize( varargin )
% Uses the resting-state image calculated using
% avg_NII_rest() to normalize the rest of the data

% If no inputs are given, the "open file..." UI will
% prompt for the required information.

%% Setup
switch length(varargin)
   case 0
      fold_name = uigetdir('Directory Containing Data');
      if ~fold_name % Cancel Button
         return
      end

      [rest_file rest_path rest_index]= uigetfile('*.nii',
         'Resting State NIFTI File');
      switch rest_index
         case 0
            return
         case 1
            rest_dat = load_nii(fullfile(rest_path,rest_file));
            rest_dat = double(rest_dat.img);
         otherwise
            error('An error has occured loading the resting
                   state data')
   end
[mask_file mask_path mask_index] = uigetfile('*nii','Mask');

switch mask_index
    case 0
        return
    case 1
        mask_dat = load_nii(fullfile(mask_path, mask_file));
        mask_dat = logical(mask_dat.img);
        if max(size(mask_dat) ~= size(rest_dat))
            error('The Mask and Resting State files must have the same size')
        end
    otherwise
        error('An error has occurred loading the resting state data')
end

case 1
    fold_name = varargin{1};
    [rest_file rest_path rest_index] = uigetfile('*nii','Resting State NIFTI File');
    switch rest_index
        case 0
            return
        case 1
            rest_dat = load_nii(fullfile(rest_path, rest_file));
            rest_dat = double(rest_dat.img);
        otherwise

```matlab
error('An error has occurred loading the resting state data')

case 2
    fold_name = varargin{1};
    rest_dat = loadNII(varargin{2});
    [mask_file mask_path mask_index] = uigetfile('*.nii','Mask ');
    switch mask_index
        case 0
            return
        case 1
            mask_dat = load_nii(fullfile(mask_path, mask_file))
            mask_dat = logical(mask_dat.img);
            if max(size(mask_dat) ~= size(rest_dat))
                error('The Mask and Resting State files must have the same size')
            end
        otherwise
            error('An error has occurred loading the resting state data')
        end
    end
            case 3
    fold_name = varargin{1};
    rest_dat = loadNII(varargin{2});
    mask_dat = loadNII(varargin{3});
    otherwise
        return
```
% Go to the folder containing the files
oldfold = cd(fold_name);
file_list = dir('*.nii');
file_count = length(file_list);

% Make a directory to save the normalized data to
saveDir = 'Normalized_to_rest';
if ~isdire(saveDir)
    mkdir(saveDir);
end

statusbar = waitbar(0,'Initializing');

% for each file: load it, divide by the rest state and save it
for i=1:file_count
    try
        waitbar(i/file_count,statusbar,[fold_name sprintf('%d%%',
            round((i/file_count)*100))]);
    catch err
        return
    end
    [file_path file_name file_ext] = fileparts(file_list(i).name);
    file_hold = load_nii(file_list(i).name);
    file_hold.img = double(file_hold.img) ./ rest_dat - 1;
    file_hold.img(~mask_dat) = 0;  % set everything outside the mask to 0
    file_hold.img(isnan(file_hold.img)) = 0;  % set all NaN's to 0
file_hold.img(isinf(file_hold.img)) = 0; % set all inf’s to 0
file_hold.img(file_hold.img == -1) = 0; % correct these for
    voxels that are giving me problems
file_hold.hdr.dime.datatype = 16; % set the datatype to single
file_hold.hdr.dime.bitpix = 16;
save_nii(file_hold,fullfile(saveDir,[file_name '_rn' file_ext])
)
end

close(statusbar)
cd(oldfold)
end

A.2.4 BOLDtoMF()

function [ ] = BOLDtoMF( varargin)
%BOLDtoMF Calculate metabolism and blood from from BOLD response
%
% Input: Directory containing a series of *.nii files of the BOLD
% response.
%
% Output: Two new files will be created in a new subdirectory
% with a variable for each time step.
%
% Usage:
% BOLDtoMF
% BOLDtoMF(directory)
%
% If a directory is not provided, one will be requested.
Method from Sotero, et. al. 2011

% =========
% = Setup =
% =========
% if a folder isn’t an argument, it’ll prompt for one
switch length(varargin)
    case 0
        fold_name = uigetdir;
        if ~fold_name  % Cancel Button pressed
            return
        end
    case 1
        fold_name = varargin{1};
    otherwise
        error('Input is not understood')
end

% Go to the folder containing the files
oldfold = cd(fold_name);
file_list = dir('*.nii');
file_count = length(file_list);

% Set up a directory for the outputs
newFolder = ['Output_', datestr(clock,1)];
mkdir(newFolder)

% Make *.mat files to append the data to
m0001 = 0; f0001 = 0;
save(['./ ' newFolder '/m.mat'],'m0001');
save(['./ ' newFolder '/f.mat'],'f0001');
s = loadNII(file_list(1).name);
norm = ones(size(s));

% ===========
% = Do Work =
% ===========

% This will calculate the metabolism and blood flow. The output is
% appended to 'm.mat' and 'f.mat' within a new folder created
% within the directory containing the data.

statusbar = waitbar(0,'Initializing');

maxBOLD = 0.22;

% Required Parameters
% [alpha beta a b c A ]
p = [0.4 1.5 0.1870 0.1572 -0.6041 maxBOLD];

% Calc flow and metabolism for when BOLD = 1
s = 0;
y = -((p(4)*p(2))/(p(1)+p(2)*p(5)))*((p(6)-s)/(p(6)*p(3)^p(2))
  ^((1/(p(1)+p(2)*p(5))));
fNOACT = -((p(1)+p(2)*p(5))/(p(4)*p(2)))*lambertw(y);
mNOACT = p(3)*fNOACT^(p(5)+1)*exp(-p(4)*fNOACT);
%%% Calc flow and metabolism

disp(fold_name)

for j=1:file_count
    try
        waitbar(j/file_count, statusbar, sprintf('%d%%', round((j/file_count)*100)));
        catch err
            return
        end
    end
    s = loadNII(file_list(j).name); % Load up the file
    s(isnan(s)) = 1;
    s(isinf(s)) = 1;
    y = -((p(4)*p(2))/(p(1)+p(2)*p(5))).*((p(6)-s)/(p(6)*p(3)^p(2))).^(1/(p(1)+p(2)*p(5)));
    if (size(y,1)==91)&&(size(y,2)==109)&&(size(y,3)==91)
        f = -((p(1)+p(2)*p(5))/(p(4)*p(2))).*lambw_mex(real(y));
    else
        f = -((p(1)+p(2)*p(5))/(p(4)*p(2))).*lambw(y);
    end
    m = p(3)*f.^(-p(5)+1).*exp(-p(4)*f);
    % Clean up NaNs that may have popped up
    m(isnan(m)) = 1;
    f(isnan(f)) = 1;
    % Normalize to resting m and f
    m = m./mNOACT;
    f = f./fNOACT;
    % Rename and save the data
eval(['m' sprintf('%04d',j) ' = m;']);
eval(['f' sprintf('%04d',j) ' = f;']);
eval(['save(''./ '' newFolder '/m.mat'', ''m'' sprintf('%04d',j) ' ' '',''','-append''));']);
eval(['save(''./ '' newFolder '/f.mat'', ''f'' sprintf('%04d',j) ' ' '',''','-append''));']);
clear m0* f0*
end

close(statusbar)
cd( oldfold)
end

A.2.5 lambw() and lambw_mex()

The lambw() function is a wrapper for the wapr() function available on Matlab FileExchange (http://www.mathworks.com/matlabcentral/fileexchange/3644-real-values-of-the-lambert-w-function/content/Lambert/wapr.m). A compiled version of this function (lambw_mex()) runs much faster and is recommended. This function is used over Matlab’s built-in Lambert-W function for the sake of performance.

function [ array_out ] = lambw( array_in )
% lambw Wrapper for wapr()
% Available: http://www.mathworks.com/matlabcentral/fileexchange/3644-real-values-of-the-lambert-w-function/content/Lambert/wapr.m
% Dwapr() doesn’t work any arrays over Nx1, so this steps through
% the full matrix and gives the rows to wapr. Works pretty fast.
%#codegen
if ndims(array_in) ~= 3
error('This only works (for now) with a three dimensional array.
')
end

xmax = size(array_in,1);
ymax = size(array_in,2);

array_out = zeros(size(array_in));
for ix=1:xmax
    for iy=1:ymax
        array_out(ix,iy,:) = wapr(array_in(ix,iy,:));
    end
end
end
A.3 Calculating the Equilibrium Temperature

In order to determine the temperature fluctuations due to changes in activity, the baseline temperature must first be established for each voxel. The function tempCalcEquilibrium() will update the temperature using the Penne's bioheat equation (Eq. (2.4)) until the change in temperature for each voxel falls below a certain threshold. Details about this procedure are available in section 2.2.2.

A.3.1 tempCalcEquilibrium()

```matlab
function temperature_Out = tempCalcEquilibrium(tissue,bloodT,airT,
    nt,tmax,pastCalc,printprogress)

% tempCalcEquilibrium Find the equilibrium values
% tissue: holds all of the structural information
% bloodT: Temperature of the blood
% airT: Temperature of the surrounding air
% nt: Max number of time steps
% tmax: Total amount of time the simulation should run over
%
% This is based off of tempCalc() but loops until the rate of
% change of each voxel is sufficiently small then outputs
% what's calculated. If it takes too long to do all at once,
% split it up into smaller time chunks and use the last step
% from the previous dataset as pastCalc in order to resume.
%
% Note: This does not save the time course because it can take
% a lot of step to find the equilibrium. It outputs the last
% time step.
%
% Written by Greggory Rothmeier (greggroth@gmail.com)
```
tic

%%% Default Values

if nargin <2, bloodT = 37; end
if nargin <3, airT = 24; end
if nargin <4, nt = 100; end
if nargin <5, tmax = 50; end
if nargin <6, pastCalc = 0; end
if nargin <7, printprogress = 1; end

% These rescue the data if the calculation is interrupted.

global temperature
global dirty

c = onCleanup(@InterCatch);
dirty = 1;

dx = 2*10^-3;  % Voxel size (m)

if nt<(2*tmax),
    warning('Time step size is not large enough. Results will be unreliable. Consider increasing the number of steps or reducing tmax.')
end

% Constants used that aren't already stored in tissue

[ xmax ymax zmax t ] = size(tissue);
clear t;
dt = tmax/(nt-1);
% rhoBlood = 1057;
% wBlood = 1000;
% cBlood = 3600;

% =========
% = Setup =
% =========
% Starts all tissue voxels at bloodT (default 37) and maintains
% air at airT (default 24)
% The condition squeeze(tissue(:,,:,:,:))~=airIndex picks out the
% elements that are tissue

temperature = ones(3,xmax,ymax,zmax,'single')*airT;
if pastCalc == 0
    temperature(1,squeeze(tissue(:,,:,:,:))~=1) = bloodT;
else
    temperature(1,:,,:) = pastCalc;
end
numElements = numel(temperature(1,:,,:));

% =========
% = Do Work =
% =========
% This is a vectorized version of the next section. For the love
% of god don’t make any changes to this without first looking below
% to make sure you know what you’re changing. This is [nearly]
% impossible to understand, so take your time and don’t break it.
% data is stored in 'tissue' as such:
% [tissuetype 0 Qm c rho k w]; <-- second element is blank for all. 
% [ 1 2 3 4 5 6 7]

averagedk = (circshift(tissue(:,:,6),[1 0 0])+circshift(tissue(:,:,6),[-1 0 0])+circshift(tissue(:,:,6),[0 1 0])+circshift(tissue(:,:,6),[0 -1 0])+circshift(tissue(:,:,6),[0 0 1])+circshift(tissue(:,:,6),[0 0 -1])+tissue(:,:,6)) / 7;
rhoblood = 1057;
chblood = 3600;

%% Specify Percision Goal

tolerance = 1; % fraction of voxels have a slope less than 'zeropoint'
zeropoint = 2.5e-7; % point at which the slope between two *steps* is considered essentially zero


goal = numElements - tolerance * numElements;
goon = numElements; % Forces the while loop to run the first time

format shortG;
% temperature(1,:,:,:) = Current Temperature
% temperature(2,:,:,:) = Next Temperature
% Resets after each update
if printprogress
    disp(['Goal: ', num2str(goal),' remaining voxels'])
end
t2 = 1;
while goon(1)>goal && t2<=nt % runs until either 'goal' elements have a slope greater than 'zeropoint' or it exceeds nt

    if printprogress
        disp([t2 goon(1) ((numElements-goon(1))/numElements)*100]) % progress
    end

    temperature(2,:,:,:) = squeeze(temperature(1,:,:,:)) + ...

    dt/(tissue(:,:,5).*tissue(:,:,4)).* ...

    ((averagedk/dx^2).*...

    (circshift(squeeze(temperature(1,:,:,:)),[1 0 0])-2*squeeze(temperature(1,:,:,:))+circshift(squeeze(temperature(1,:,:,:)),[-1 0 0])+... % shift along x

    circshift(squeeze(temperature(1,:,:,:)),[0 1 0])-2*squeeze(temperature(1,:,:,:))+circshift(squeeze(temperature(1,:,:,:)),[0 -1 0])+... % shift along y

    circshift(squeeze(temperature(1,:,:,:)),[0 0 1])-2*squeeze(temperature(1,:,:,:))+circshift(squeeze(temperature(1,:,:,:)),[0 0 -1]))... % shift along z

    -(1/6000)*rhoblood*tissue(:,:,7)*cblood.*(squeeze(temperature(1,:,:,:))-bloodT)+tissue(:,:,3));

    % resets the air temperature back since it’s also modified

    % above, but it needs to be kept constant throughout the % calculations

    temperature(2,squeeze(tissue(:,:,1))==1) = airT;

    % checks how quickly the temperature is changing and if it is % close enough to zero to be considered stopped ('zeropoint ')

    goon = size(temperature(abs(squeeze(temperature(2,:,:,:))-
        temperature(1,:,:,:)))>zeropoint));

    temperature(1,:,:,:) = temperature(2,:,:,:);
t2 = t2 + 1;

end

temperature_Out = temperature(2,:,:,:);
dirty = 0;

% equilTemperature = temperature_Out;
% save(’equil.mat’,’equilTemperature’);

%% To Combine Datasets
% use this technique if there are separate datasets that need
% combining
% vertcat(squeeze(res1(:,,:,:)),squeeze(res2(2:end,:,:,:)))
% Where for all by the first dataset, you need to do the time from
% 2:end so that there are no repeats (remember that the last
% timestep from the previous dataset serves as the first for the
% new one)

time = toc;

end

% Recovers the data if calculation was interrupted
function InterCatch
global dirty
if dirty
    disp(’Interrupt Intercepted. Inpreptating Interworkspace Data Interfaces.’)
    global temperature
equilibriumT = temperature;

save('equiltempAbortDump.mat','equilibriumT');

% setappdata(0,'InterpOut',temperature);
end
end
A.4 Calculating the Temperature Change

The following function takes as inputs the head data matrix (appendix A.1), the metabolism and blood flow time courses (appendix A.2) and the equilibrium temperatures (appendix A.3) and calculates the temperature time-course. More details about this algorithm can be found in section 2.2.4.

A.4.1 tempCalcDynMF

```matlab
function temperatureOut = tempCalcDynMF(tissue,bloodT,airT,nt,tmax,
                                        pastCalc,metab,flow,savesteps,region)

% tempCalcDynMF How does changing metabolism and blood flow
% affect things?

% tissue: holds all of the structural information
% bloodT: Temperature of the blood
% airT: Temperature of the surrounding air
% nt: Number of time steps
% tmax: Amount of model time the simulation should span

% region: logical matrix same size as head that is used as a mask

% Written by Greggory Rothmeier (greggroth@gmail.com)
% Georgia State University Dept. Physics and Astronomy
% May, 2011

statusbar = waitbar(0,'Initializing');

%%% Default Values
```
if nargin<2, bloodT = 37; end
if nargin<3, airT = 24; end
if nargin<4, nt = 3; end
if nargin<5, tmax = 1; end
if nargin<6, pastCalc = 0; end

% Length of one side of a voxel (m)
dx = 2*10^-3;

if nt<(2*tmax),
    warning('Time step size is not large enough. Results will be unreliable. Consider increasing the number of steps or reducing tmax. ')
end

[xmax ymax zmax t] = size(tissue);
clear t;
dt = ones([xmax ymax zmax])*tmax/(nt-1);

%% Determine Metabolism/Blood Flow Data Storage System
if ischar(metab)&&(ischar(flow))
    % if file locations are given rather than data
    option = 1;
else
    % Preallocate matrices for holding metabolism and blood flow data
    metabMulti = ones([xmax ymax zmax],'single');
    flowMulti = ones([xmax ymax zmax],'single');
    option = 0;

end
end

%% Maps
% Creates a map that identifies where there is tissue
% the condition squeeze(tissue(:,:,:,:))~=airIndex picks out the
% elements that are tissue

max = ceil((nt-1)/savesteps);

temperatureOut = ones(tmax,xmax,ymax,zmax,'single');
temperature = ones(2,xmax,ymax,zmax,'single')*airT;

if pastCalc == 0
    temperature(1,squeeze(tissue(:,:,1))~=1) = bloodT;
else
    % Starts everything off at the pre-determined equilibrium
    temperatures
    temperature(1,:,:,:) = pastCalc(end,:,:,:);
end

temperatureOut(:,:,1) = temperature(:,:,1);

% ===========
% = Do Work =
% ===========

% This is a vectorized version of the next section. For the love
% of god don’t make any changes to this without first looking below
% to make sure you know what you’re changing. This is [nearly]
% impossible to understand because it’s been vectorized, so take
% your time and don’t break it. Data is stored in ’tissue’ as such


averagedk = (circshift(tissue(:,:,:,:),[1 0 0]) + circshift(tissue(:,:,:,:),[-1 0 0]) + circshift(tissue(:,:,:,:),[0 1 0]) + circshift(tissue(:,:,:,:),[0 -1 0]) + circshift(tissue(:,:,:,:),[0 0 1]) + circshift(tissue(:,:,:,:),[0 0 -1]) + tissue(:,:,:,:))/7;

rho = 1057;

c = 3600;

%% Only saves every 4 steps to reduce the final matrix size
for t2 = 1:nt-1
    waitbar(t2/(nt-1),statusbar,sprintf('%d%% ',round(t2/(nt-1)*100)));

    % if a variable needs to be used multiple times for the same time step.
    t3 = floor((t2-1)/4)+1; % 1 1 1 1 2 2 2 2 3 3 . . .

    % if a file is specified, pulls the data from the file for each step
    if option
        eval(strcat('load(fullfile(metab),''-mat'',''m'',sprintf(''%d'',t3),''''));'));
        eval(strcat('load(fullfile(flow),''-mat'',''f'',sprintf(''%04d'',t3),''''));'));

        eval(strcat('metabMulti = m'',sprintf(''%04d'',t3),''''));
        eval(strcat('flowMulti = f'',sprintf(''%04d'',t3),''''));
    end
```matlab
eval(strcat('clear f', sprintf('%04d',t3), 'm', sprintf('%04d',t3)))

else
    metabMulti(region) = metab(t2);
    flowMulti(region) = flow(t2);
end

temperature(2,:,:,:) = squeeze(temperature(1,:,:,:)) + ...
    dt./(tissue(:,:,:,:)*tissue(:,:,:,:))... *
    ((averagedk/dx^2).* ...
    (circshift(squeeze(temperature(1,:,:,:)),[1 0 0])-2*squeeze
    (temperature(1,:,:,:))+circshift(squeeze(temperature
    (1,:,:,:)),[-1 0 0])+... % shift along x
    circshift(squeeze(temperature(1,:,:,:)',[0 1 0])-2*squeeze
    (temperature(1,:,:,:))+circshift(squeeze(temperature
    (1,:,:,:)),[0 -1 0])+... % shift along y
    circshift(squeeze(temperature(1,:,:,:),[0 0 1])-2*squeeze
    (temperature(1,:,:,:))+circshift(squeeze(temperature
    (1,:,:,:)],[0 0 -1]))... % shift along z
    -(1/6000)*rhoblood*flowMulti.*tissue(:,:,:,:)*cblood.*(s
    squeeze(temperature(1,:,:,:))-bloodT)+metabMulti.*
    tissue(:,:,:,:));

% resets the air temperature back since it's also modified
    above,
% but it needs to be kept constant throughout the calculations
temperature(2,squeeze(tissue(:,:,:,:))==1) = airT;
temperatureOut(ceil(t2/savesteps),:,:) = temperature(2,:,:,:)
;
temperature(1,:,:) = temperature(2,:,:);
```

clear metabMulti flowMulti

end

close(statusbar);

% ============
% = Old Code =
% ============
% This is what used to be used. It's much slower (~60 times
% slower), but it's much easier to understand compared to the
% above code. If any changes need to be made above, first look
% through this code to ensure you understand it before making
% changes. It's really easy to mess up the code above and nearly
% impossible to figure out where.
%
% good luck.
%
% for t2 = 1:nt-1
% for x2 = 2:xmax-1
% for y2 = 2:ymax-1
% for z2 = 2:zmax-1
%  if tissue(x2,y2,z2,1) ~= 1,
%  temperature(t2+1,x2,y2,z2) = temperature(t2,
%   x2,y2,z2) + (dt/(tissue(x2,y2,z2,5)*tissue(x2,y2,z2,4)))*((tissue
%   (x2,y2,z2,6)/dx^2)*...
%  )
%  (temperature(t2,x2+1,y2,z2)-2*temperature( 
%   t2,x2,y2,z2))+temperature(t2,x2-1,y2,z2)+...
%  temperature(t2,x2,y2+1,z2)-2*temperature(t2 
%   ,x2,y2,z2)+temperature(t2,x2,y2-1,z2)+...
% temperature(t2,x2,y2,z2+1)-2*temperature(t2,x2,y2,z2)+temperature(t2,x2,y2,z2-1)...
% -(1/6000)*rhoBlood*wBlood*cBlood*(temperature(t2,x2,y2,z2)-bloodT)+tissue(x2,y2,z2,3));
%
end
end
end
end
end
end
end
end
end
end
end
Appendix B  Visualization Tools

The temperature data is a four dimensional dataset (time, x, y and z), so good visualizations tools are necessary to analyzing the results. The primary tool I use is a modification of SliceBrowser (http://www.mathworks.com/matlabcentral/fileexchange/20604) and is provided as part of temptools (https://github.com/greggroth/temptools/tree/master/lib/SliceBrowser). In working with this, I also created a function (TempPlot()) to act as a wrapper and handle possible plotting situations depending on the number of inputs.

B.1.1 TempPlot()

```matlab
function [ ] = TempPlot( head, tempdata, highlightRegion, slice,
equil,threshold,point)

% TempPlot Plot data from tempCalc() or BulkImportNII()
% INPUT TempPlot(structuredata)
% TempPlot(structuredata,temperaturedata)
% TempPlot(structuredata,temperaturedata,highlightRegion)
% TempPlot(structuredata,temperaturedata,highlightRegion,
slice)
% TempPlot(structuredata,temperaturedata,highlightRegion,
slice,EquillibriumData)

% This function with determine which type of data it is and then
% plot it appropriately.

% equil - Equillibrium state data
% threshold - threshold value for being displayed as an overlay

% REQUIRES: SliceBrowser (http://www.mathworks.com/matlabcentral/fileexchange/20604)
```
%% Error checking and data restructuring where necessary
if ndims(head) == 4
    head = head(:,:,1);
elseif ndims(head) ~= 3
    error('Input ''head'' must have either 3 or 4 dimensions');
end

if nargin > 1
    if ndims(tempdata) == 3 % should only happen when comparing
        two equilibrium datasets
        temp = tempdata;
        tempdata = zeros([1 size(temp)]);
        tempdata(1,:,:,:) = temp;
    elseif ndims(tempdata) ~= 4
        error('Input ''tempdata'' must have either 3 or 4 dimensions');
    end
    tempdataShort = squeeze(tempdata(end,:,:,:));
end

if nargin > 2
    if ndims(highlightRegion) ~= 3
        error('Input ''highlightRegion'' must have 3 dimensions');
    end
    if size(highlightRegion) ~= size(head)
        error('Input ''highlightRegion'' must be of the same size as ''head''');
    end
    tempdataShort = squeeze(tempdata(end,:,:,:));
if nargin > 3
    if slice > size(tempdata,1)
        error('Input ''slice'' must be less or equal to the length of the first dimension of ''tempdata''');
    end
    tempdataShort = squeeze(tempdata(slice,:,:,:));
end

if nargin > 4
    if ndims(equil) == 3
        eq = equil;
    elseif ndims(equil) == 4
        eq = squeeze(equil(1,:,:,:));
    else
        error('Input ''equil'' must have either 3 or 4 dimensions');
    end
    clear 'equil';
end

%% Pick how to format the call of SliceBrowser()
switch nargin
    case 1
        SliceBrowser(head,1,head);
        colormap(gray);
    case 2
        SliceBrowser(tempdataShort,tempdata,head);
B.1.2 tsliceplot

This is a visualization tool I wrote that allows you to view the change in temperature versus time for a line passing through the head. Screenshots of the tool can be seen in Figs. B.1 and B.2.

Usage:

```
tsliceplot(temperature_data, equilibrium_temperature_data)
```

or

```
tsliceplot(change_in_temperature_data)
```

The inputs `temperature_data` and `change_in_temperature_data` should be four dimensional matrices (time, x,y,z) and `equilibrium_temperature_data` is also a four dimensional matrix (1,x,y,z).

The script is available as part of temptools ([https://github.com/greggroth/temptools/tree/master/lib/tsliceplot](https://github.com/greggroth/temptools/tree/master/lib/tsliceplot)).
Figure B.1  Experimental data for activity in the motor cortex visualized with tsliceplot.
Figure B.2  The same data as is presented in Fig. B.1, but viewed flat-on along the z vs. time plane.